



ETH Shaping the future

Roboter verlassen die Produktionshallen

Prof. Dr. Roland Siegwart

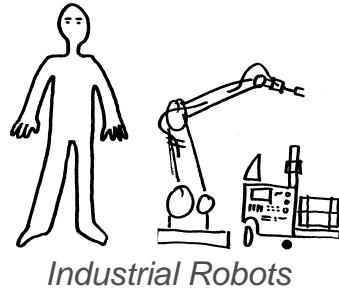
www.asl.ethz.ch

www.wysszurich.ch

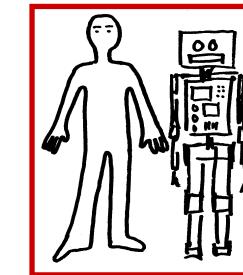
*18. Thurgauer Technologietage
UNIMA AG, MATZINGEN, 23.03.2018*

Nächste Generation von Robotern

| mobil, verbunden, intelligent, adaptiv und unter uns



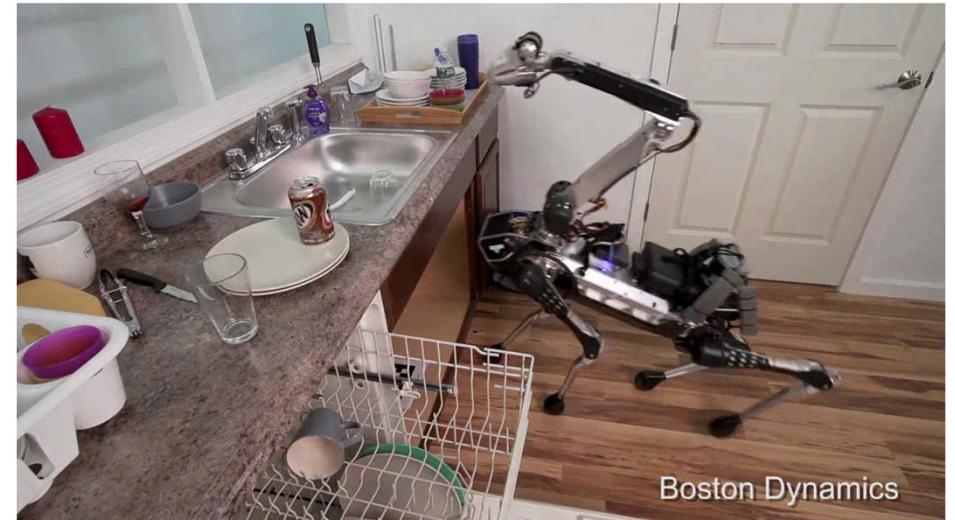
Industrial Robots



Service Robots



<https://www.youtube.com/watch?v=SeloQy0oXjI>



<https://www.youtube.com/watch?v=tf7IEVTDjng>

Serviceroboter | die Herausforderungen

- Roboter müssen mit *unsicherer* und nur *teilweise verfügbarer multimodaler Information* umgehen können.
- Roboter müssen *sehen, spüren* und *verstehen* können.
- Roboter müssen *taktil* mit der Umgebung interagieren können
→ («soft robots» mit Kraftreglung)
- Roboter müssen *intuitiv programmierbar* sein
- Roboter müssen *lern- und anpassungsfähig* sein
→ **Um das zu erfüllen, braucht es Künstliche Intelligenz, aber auch neue Sensoren, Aktoren und Roboterkonzepte**



50x speed
<https://www.youtube.com/watch?v=gy5g33S0Gzo>



Roland Siegwart 19.03.2018 6

Service Robots

– wheeled and walking robots for challenging tasks

BeachBot (with Disney) – developed by students

| the beach artist

<https://www.youtube.com/watch?v=eBRrQBPtak>



Vertigo – developed by students

| the ultimate wall climber

<https://www.youtube.com/watch?v=KRYT2kYbgo4>



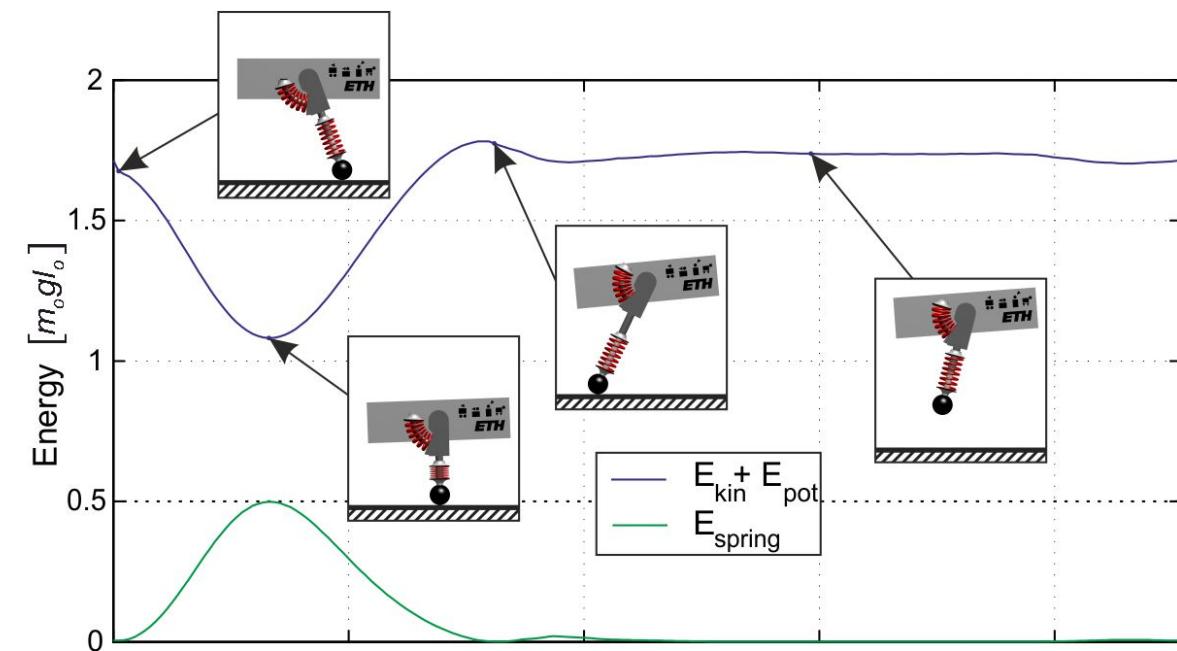
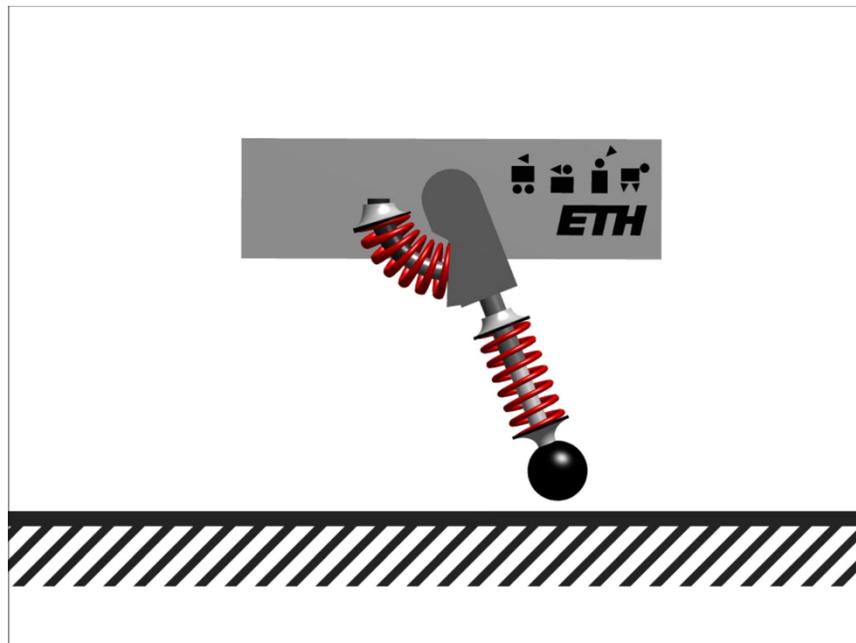
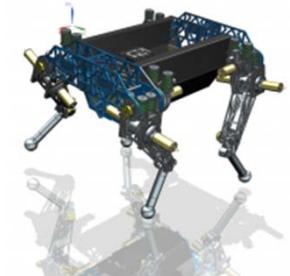
Efficient Walking and Running |

what nature evolved (Extreme Jumpy Dog)



- <http://www.youtube.com/watch?v=Jql6TSyudFE>

Efficient Walking and Running | serial elastic actuation



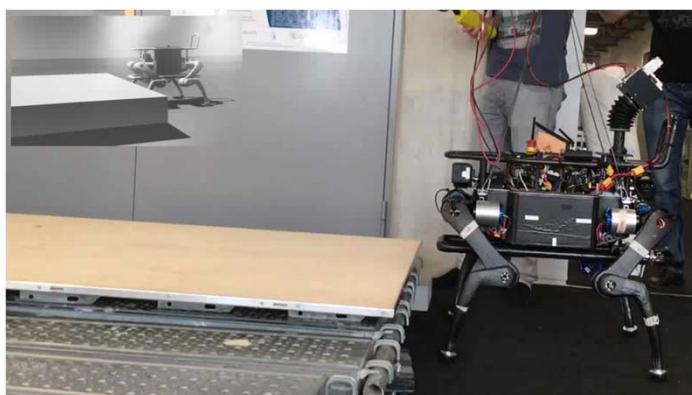
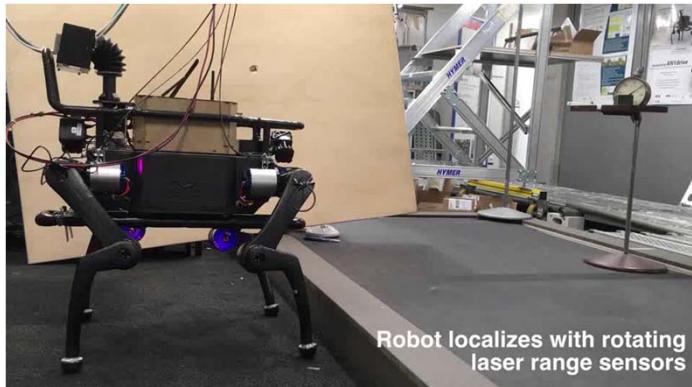
<https://www.youtube.com/watch?v=6igNZiVtbxU>

ANYmal

Combining dynamic motion skills with large mobility



RSL
Robotic Systems Lab
Prof. Marco Hutter



Service Robots – flying robots for challenging tasks

wingtra – developed by students

| the VTOL UAV

<https://www.youtube.com/watch?v=QADvPDWtgFU>



| 81 hours non-stop in summer 2015

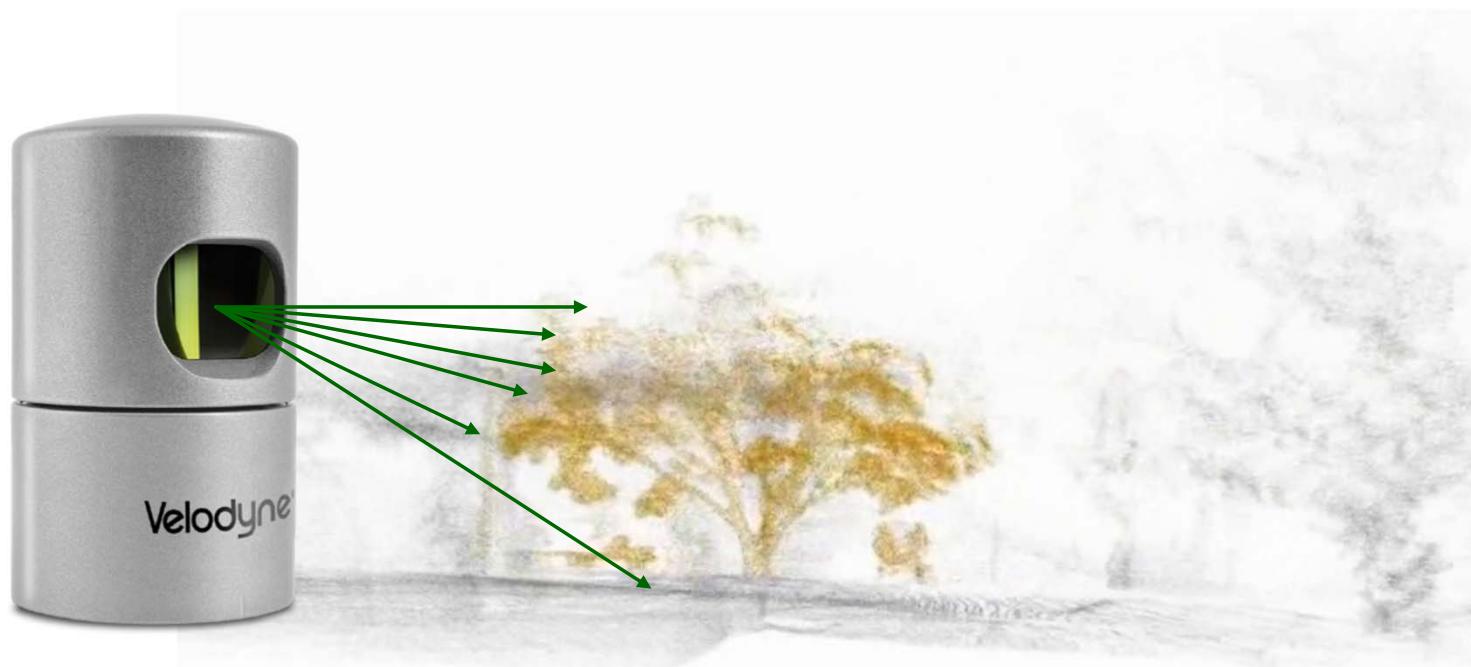
| 5.64 m, 6.2 kg

https://www.youtube.com/watch?v=8m4_NpTQn0E

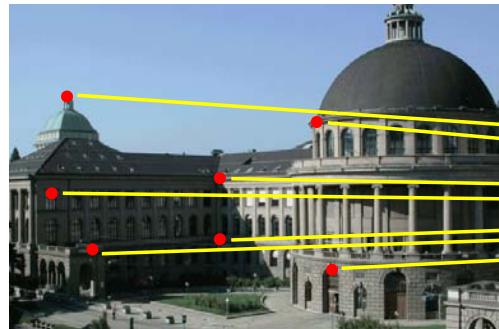
https://www.youtube.com/watch?v=wyS6W1t_ryQ



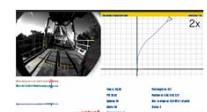
“Sehen” | Laser-basierte 3D Pläne



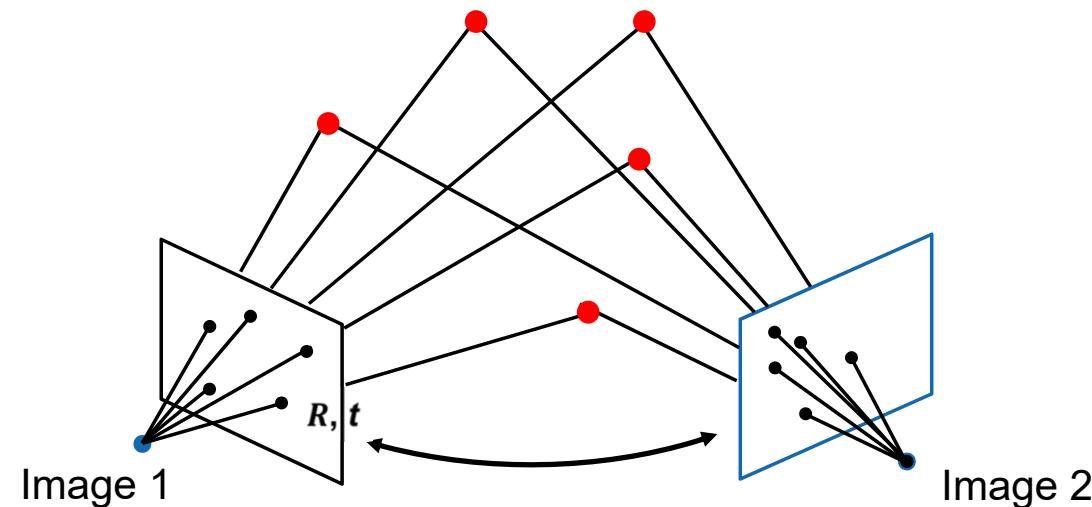
“Sehen” | Bewegungsschätzung mit Kamera und Inertialsensor (IMU)



Google
Project Tango



<https://www.youtube.com/watch?v=yvgPrZNp4So>



Autonomous Cars Today | cameras (lane tracking, ...) → no map

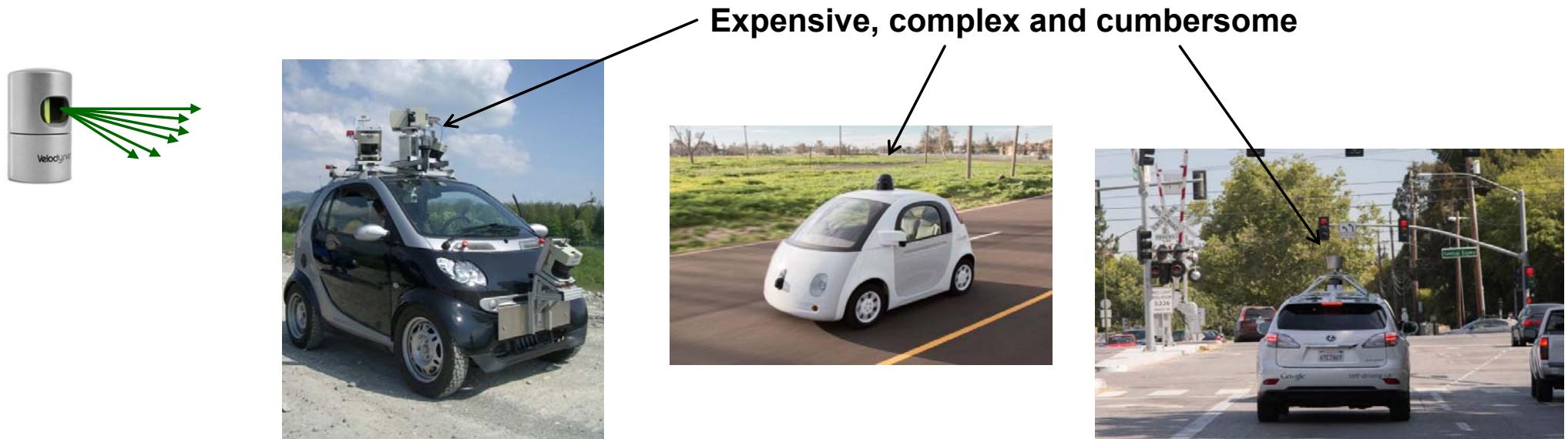


- Detection and tracking of ...
 - Lanes,
 - street signs,
 - other cars,
 - ...

<https://www.youtube.com/watch?v=aGW4nRzx8lw>



Today | 3D laser sensors → map based

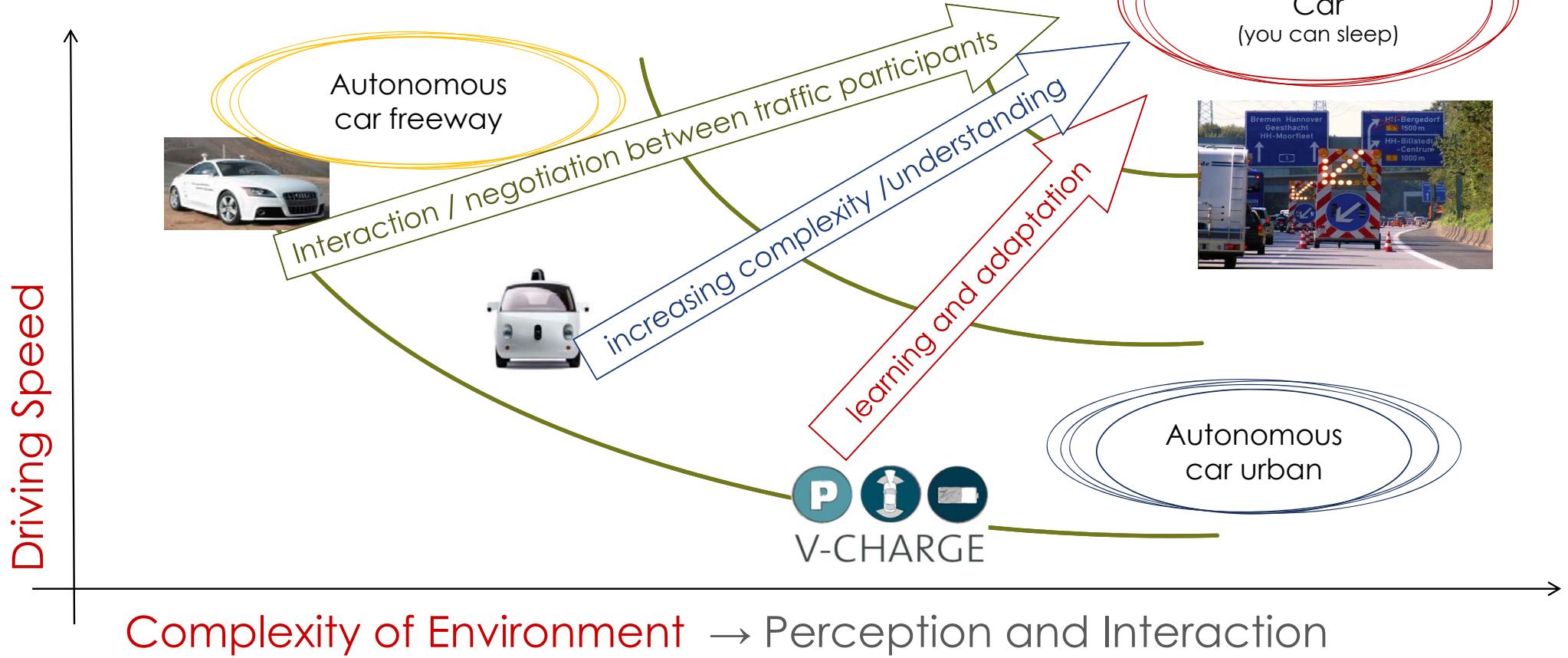


- Google Self-Driving Car Project (status summer 2015)
 - > 20 vehicles in use
 - > 2,7 mio km, 1.5 mio km in autonomous mode
 - > 11 accidents
 - No people insured
 - Non of them caused by car control algorithm



<https://www.youtube.com/watch?v=eJCR2TaeSFc>

Autonomous Cars | roadmap

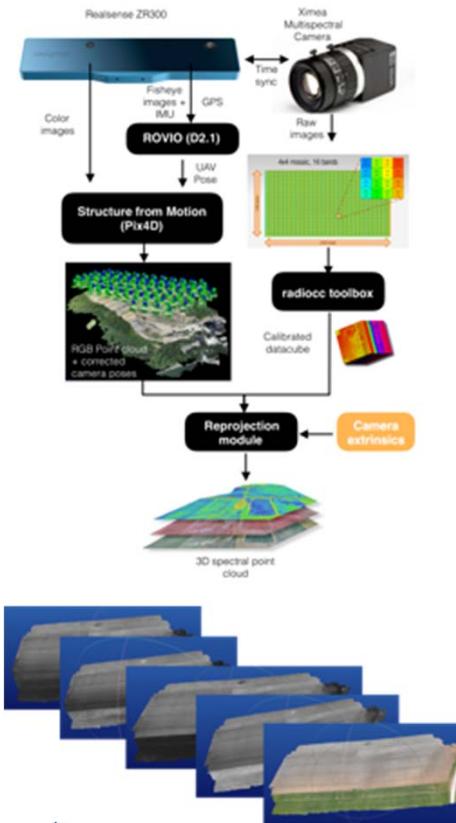


Autonomous Cars | a bright future without traffic jams



Flourish – Aerial Data Collection and Analysis, and Automated Ground Intervention for Precision Farming

Spatio-Temporal Spectral Environment Modeling

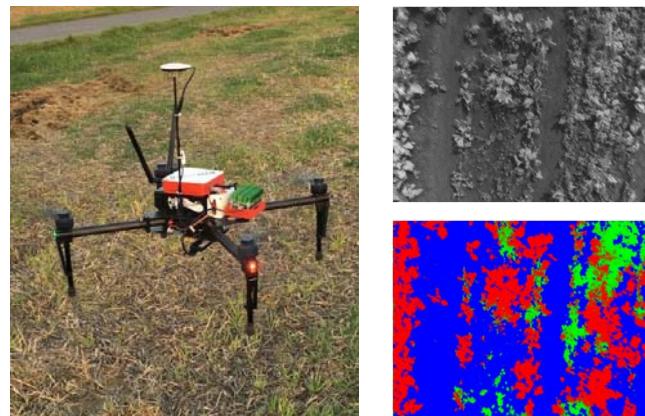


<https://youtu.be/5f1Etfw76Qc>

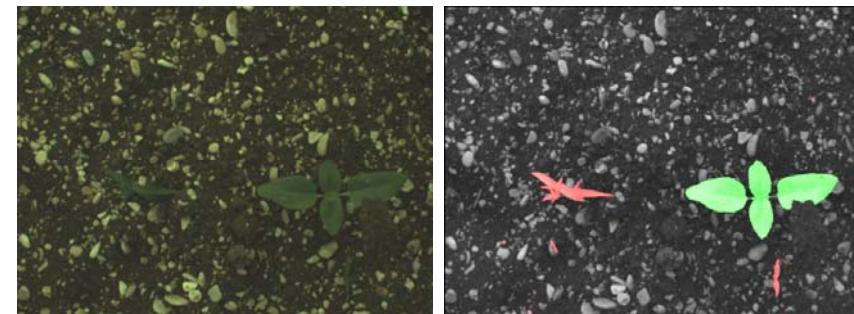
Autonomous UAV landing



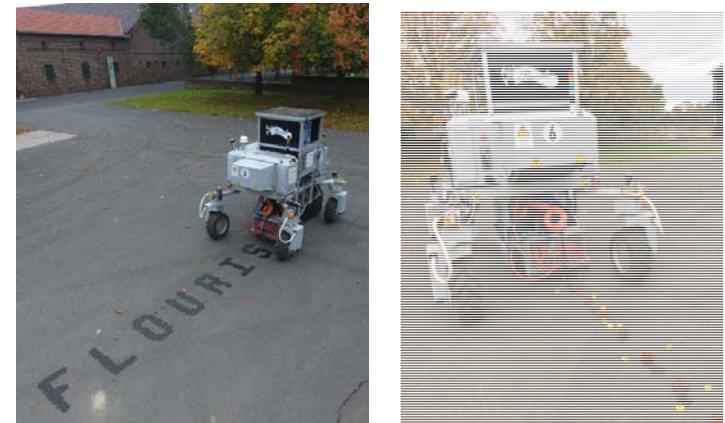
UAV onboard weed detection



Weed classification on UGV (Sunflower ~95% acc.)



Automated spraying and stamping



Navigation & Planning in Cluttered Environments



<https://www.youtube.com/watch?v=rAJwD2kr7c0>

*Complexity
of Services*

Tactile
Manipulation

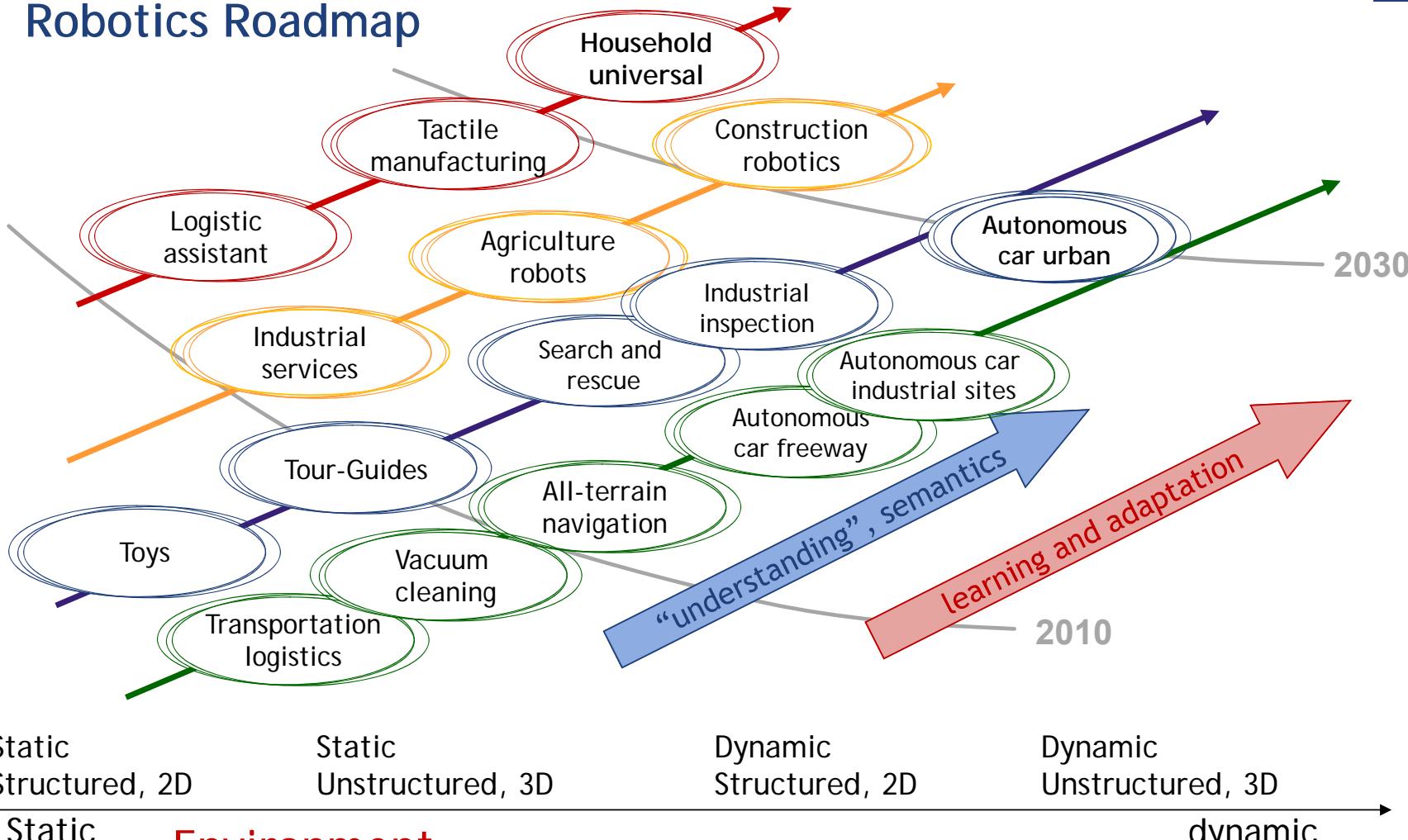
Mobile
Manipulation

Advanced
Interaction

Autonomous
Navigation

Actions - from simple motion to complex interaction

Robotics Roadmap



Environment - from static 2D grid maps to 3D cognitive maps

Switzerland | a melting pot for robotics technology

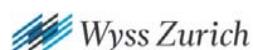
Initiatives



Spin-offs (* ASL)



*



Industrial Collaborations (ASL)



Take Home Message

- Ja, Robotik boomte
 - ... es braucht aber noch viel F&E um diese komplexen Systeme auf den Markt zu bringen.
- Ja, Europa und speziell die Schweiz hat das Potential diesen wichtigen Markt zu erobern und somit nachhaltig Arbeitsplätze zu schaffen. Es geht um:
 - Hervorragende Forschung und grossartige Talente
 - Präzisionsmechanik und Künstliche Intelligenz
 - Innovation und Unternehmertum
- Für die Skalierung von Robotik-Technologie und Startups brauchen wir Talente, mehr **Risikobereitschaft und langfristig ausgerichtetes Risikokapital (> 10 Jahre)**



On a Swiss roll: Sophia, a human-like robot developed by Hanson Robotics. Mountains, lakes, chocolate, fondue and banks? Right? Only partly. The Alpine nation is now "the Silicon Valley of robotics," according to Chris Anderson, chief

